A partial introduction to financial asset pricing theory

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Abstract

We present an introduction to mathematical Finance Theory for mathematicians. The approach is to start with an abstract setting and then introduce hypotheses as needed to develop the theory. We present the basics of European call and put options, and we show the connection between American put options and backwards stochastic differential equations. © 2001 Elsevier Science B.V. All rights reserved.

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1. Introduction

Stock markets date back to at least 1531, when one was started in Antwerp, Belgium. Today there are over 150 stock exchanges (see Wall Street Journal, May 15, 2000). The mathematical modeling of such markets however, came hundreds of years after Antwerp, and it was embroiled in controversy at its beginnings. The first attempt known to the author to model the stock market using probability is due to L. Bachelier in Paris about 1900. Bachelier’s model was his thesis, and it met with disfavor in the Paris mathematics community, mostly because the topic was not thought worthy of study. Nevertheless we now realize that Bachelier essentially modeled Brownian motion five years before the 1905 paper of Einstein (albeit twenty years after T. N. Thiele of Copenhagen (Hald, 1981)) and of course decades before Kolmogorov gave mathematical legitimacy to the subject of probability theory. Poincaré was hostile to Bachelier’s thesis, remarking that his thesis topic was “somewhat remote from those our candidates are in the habit of treating” and Bachelier ended up spending his career in Besançon, far from the French capital. His work was then ignored and forgotten for some time.

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Following work by Cowles (1930s), Kendall and Osborne (1950s), it was the renowned statistician L. J. Savage who re-discovered Bachelier’s work in the 1950s, and he alerted Paul Samuelson (see Bernstein, 1992, pp. 22–23). Samuelson further developed Bachelier’s model to include stock prices that evolved according to a geometric Brownian motion, and thus (for example) always remained positive. This built on the earlier observations of Cowles and others that it was the increments of the logarithms of the prices that behaved independently.

The development of financial asset pricing theory over the 35 yr since Samuelson’s (1965) article has been intertwined with the development of the theory of stochastic integration. A key breakthrough occurred in the early 1970s when Black and Scholes (1973) and Merton (1973) proposed a method to price European options via an explicit formula. In doing this they made use of the Itô stochastic calculus and the Markov property of diffusions in key ways. The work of Black et al. brought order to a rather chaotic situation, where the previous pricing of options had been done by intuition about ill-defined market forces. Shortly after the work of Black et al. the theory of stochastic integration for semimartingales (and not just Itô processes) was developed in the 1970s and 1980s, mostly in France, due in large part to P. A. Meyer of Strasbourg and his collaborators. These advances in the theory of stochastic integration were combined with the work of Black et al. to further advance the theory, by Harrison and Kreps (1979) and Harrison and Pliska (1981) in seminal articles published in 1979 and 1980. In particular they established a connection between complete markets and martingale representation. Much has happened in the intervening two decades, and the subject has attracted the interest and curiosity of a large number of mathematicians. The interweaving of finance and stochastic integration continues today. This article has the hope of introducing mathematicians to the subject at more or less its current state, for the special topics addressed here. We take an abstract approach, attempting to introduce simplifying hypotheses as needed, and we signal when we do so. In this way it is hoped that the reader can see the underlying mathematical structure of the theory.

The subject is much larger than the topics of this article, and there are several books that treat the subject in some detail (e.g., Duffie, 1996; Karatzas and Shreve, 1998; Musiela and Rutkowski, 1997; Shiryaev, 1999). Indeed, the reader is sometimes referred to books such as (Duffie, 1996) to find more details for certain topics. Otherwise references are provided for the relevant papers.

2. Introduction to options and arbitrage

Let $X = (X_t)_{0 \leq t \leq T}$ represent the price process of a risky asset (e.g., the price of a stock, a commodity such as “pork bellies,” a currency exchange rate, etc.). The present is often thought of as time $t = 0$; one is interested in the price at time $T$ in the future which is unknown, and thus $X_T$ constitutes a “risk”. (For example, if an American company contracts at time $t = 0$ to deliver machine parts to Germany at time $T$, then the unknown price of Euros at time $T$ (in dollars) constitutes a risk for that company.) In order to reduce this risk, one may use, for example, “options”: one can purchase — at time $t = 0$ — the right to buy Euros at time $T$ at a price that is fixed at time 0, and which is called the “strike price”. This is one example of an option, called a call option.
The payoff at time $T$ of a call option with strike price $K$ can be represented mathematically as

$$H(\omega) = (X_T(\omega) - K)^+,$$

where $x^+ = \max(x, 0)$. Analogously the payoff of a put option with strike price $K$ at time $T$ is

$$H(\omega) = (K - X_T(\omega))^+,$$

and this corresponds to the right to sell the security at price $K$ at time $T$.

These are two simple examples, often called European call options and European put options. They are clearly related, and we have

$$X_T - K = (X_T - K)^+ - (K - X_T)^+.$$

This simple equality leads to relationships between the price of a call option and the price of a put option, known as put–call parity. We return to this in Section 3.7. We can also use these two simple options as building blocks for more complicated ones.

For example if

$$H = \max(K, X_T)$$

then

$$H = X_T + (K - X_T)^+ = K + (X_T - K)^+.$$

More generally if $f: \mathbb{R}_+ \to \mathbb{R}_+$ is convex we can use the well known representation

$$f(x) = f(0) + f'(0)x + \int_0^\infty (x - y)^+ \mu(dy)$$

(1)

where $f'_+(x)$ is the right continuous version of the derivative of $f$, and $\mu$ is a positive measure on $\mathbb{R}$ with $\mu = f''$, where the derivative is in the generalized function sense.

In this case if

$$H = f(X_T)$$

is our contingent claim, then $H$ is effectively a portfolio of European call options, using (1) (see Brown and Ross, 1991):

$$H = f(0) + f'_+(0)X_T + \int_0^\infty (X_T - K)^+ \mu(dK).$$

For the options discussed so far, the contingent claim is a random variable of the form $H = f(X_T)$, that is, a function of the value of $X$ at one fixed and prescribed time $T$. One can also consider options of the form

$$H = F(X)_T$$

$$= F(X_s; 0 \leq s \leq T)$$

which are functionals of the paths of $X$. For example if $X$ has càdlàg paths (càdlàg is a French acronym for “right continuous with left limits”) then $F: D \to \mathbb{R}_+$, where $D$ is the space of functions $x: [0, T] \to \mathbb{R}_+$ which are right continuous with left limits. If the options can be exercised only at the expiration time $T$, then they are still considered to
be European options, although their analysis for pricing and hedging is more difficult than for simple call and put options. An American option is one which can be exercised at any time before or at the expiration time. That is, an American call option allows the holder to buy the security at a striking price \( K \) not only at time \( T \) (as is the case for a European call option), but at any time between times \( t = 0 \) and time \( T \). (It is this type of option that is listed, for example, in the “Listed Options Quotations” in the Wall Street Journal.) Deciding when to exercise such an option is complicated. A strategy for exercising an American option can be represented mathematically by a stopping rule \( \tau \). (That is, if \( (\mathcal{F}_t)_{t \geq 0} \) is the underlying filtration of \( X \) then \( \{\tau \leq t\} \in \mathcal{F}_t \) for each \( t, 0 \leq t \leq T \).) For a given \( \tau \), the claim is then (for a classic American call) a payoff at time \( \tau(\omega) \) of

\[
H(\omega) = (X_{\tau(\omega)}(\omega) - K)^+.
\]

We now turn to the pricing of options. Let \( H \) be a random variable in \( \mathcal{F}_T \) representing a contingent claim. Let \( V_t \) be its value (or price) at time \( t \). What then is \( V_0 \)?

From a traditional point of view, classical probability tells us that

\[
V_0 = E\{H\}. \tag{2}
\]

One could discount for the time value of money (inflation) and assuming a fixed interest rate \( r \) and a payoff at time \( T \), one would have

\[
V_0 = E\left\{ \frac{H}{(1+r)^T} \right\} \tag{3}
\]

instead of (2). For simplicity we will take \( r = 0 \) and then show why the obvious price given in (2) does not work (!). For simplicity we consider a binary example. At time \( t = 0 \), 1 Euro = $1.15. We assume at time \( t = T \) the Euro will be worth either $0.75 or $1.45; the probability it goes up to $1.45 is \( p \) and the probability it goes down is \( 1 - p \).

Let the option have exercise price \( K = $1.15 \), for a European call. That is, \( H = (X_T - $1.15)^+ \), where \( X = (X_t)_{0 \leq t \leq T} \) is the price of one Euro in U.S. dollars. The classical
rules for calculating probabilities dating back to Huygens and Bernoulli give a price of $H$ as

\[ E(H) = (1.45 - 1.15)p = (0.30)p. \]

For example if \( p = 1/2 \) we get \( V_0 = 0.15 \).

The Black–Scholes method \(^1\) to calculate the option price, however, is quite different. We first replace \( p \) with a new probability \( p^* \) that (in the absence of interest rates) makes the security price \( X = (X_t)_{t=0,T} \) a martingale. Since this is a two-step process, we need only to choose \( p^* \) so that \( X \) has constant expectation. Since \( X_0 = 1.15 \), we need

\[ E^*\{X_T\} = 1.45p^* + (1 - p^*)0.75 = 1.15, \]

where \( E^* \) denotes mathematical expectation with respect to the probability measure \( P^* \) given by \( P^*(\text{Euro} = $1.45 \text{ at time } T) = p^* \), and \( P^*(\text{Euro} = $0.75 \text{ at time } T) = 1 - p^* \). Solving for \( p^* \) gives

\[ p^* = \frac{4}{7}. \]

We get now

\[ V_0 = E^*\{H\} = (0.30)p^* = \frac{6}{35} \approx 0.17. \tag{4} \]

The change from \( p \) to \( p^* \) seems arbitrary. But there is an economics argument to justify it; this is where the economics concept of the absence of arbitrage opportunities changes the usual intuition dating back to the 16th and 17th centuries.

Suppose, for example, at time \( t = 0 \) you sell the option, giving the buyer of the option the right to purchase 1 Euro at time \( T \) for $1.15. He then gives you the price \( \pi(H) \) of the option. Again we assume \( r = 0 \), so there is no cost to borrow money. You can then follow a safety strategy to prepare for the contingent claim you sold (see Table 1, calculations are to two decimal places):

Since the balance at time \( T \) is zero in both cases, the balance at time 0 should also be 0; therefore we must have \( \pi(H) = 0.17 \). Indeed any price other than \( \pi(H) = 0.17 \) would allow either the option seller or buyer to make a sure profit without any risk: this is called an arbitrage opportunity in economics, and it is a standard assumption that such opportunities do not exist. (Of course if they were to exist, market forces would, in theory, quickly eliminate them.)

Thus we see that — at least in the case of this simple example — that the “no arbitrage price” of the contingent claim \( H \) is not \( E\{H\} \), but rather must be \( E^*\{H\} \), since otherwise there would be an opportunity to make a profit without taking any risk. We emphasize that this is contrary to our standard intuition, since \( P \) is the probability measure governing the true laws of chance of the security, while \( P^* \) is an artificial construct.

\(^1\) The “Black–Scholes method” dates back to the fundamental and seminal articles Black and Scholes (1973) and Merton (1973) of 1973, where partial differential equations were used; the ideas implicit in that (and subsequent) articles are now referred to as the Black–Scholes methods. M. S. Scholes and R. Merton received the Nobel prize in economics for Black and Scholes (1973) and Merton (1973) and related work (F. Black died and was not able to share in the prize.)
Table 1

<table>
<thead>
<tr>
<th>Action at time $t = 0$</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sell the option at price $\pi(H)$</td>
<td>$+\pi(H)$</td>
</tr>
<tr>
<td>Borrow $\frac{\pi}{2}$</td>
<td>$+0.32$</td>
</tr>
<tr>
<td>Buy $\frac{1}{4}$ Euros at $1.15$</td>
<td>$-0.49$</td>
</tr>
</tbody>
</table>

The balance at time $t = 0$ is $\pi(H) - 0.17$

At time $T$ there are two possibilities:

(i) The Euro has risen:
- Option is exercised
- Sell $\frac{1}{4}$ Euros at 1.45
- Pay back loan

(ii) The Euro has fallen:
- Option is worthless
- Sell $\frac{1}{4}$ Euros at 0.75
- Pay back loan

This simple binary example can do more than illustrate the idea of using lack of arbitrage to determine a price. We can also use it to approximate some continuous models. We let the time interval become small ($\Delta t$), and we let the binomial model already described become a recombinant tree, which moves up or down to a neighboring node at each time "tick" $\Delta t$. For an actual time "tick" of interest of length say $\delta$, we can have the price go to $2^n$ possible values for a given $n$, by choosing $\Delta t$ small enough in relation to $n$ and $\delta$. Thus for example if a continuous time process follows Geometric Brownian motion:

$$dS_t = \sigma S_t dB_t + \mu S_t dt$$

(as is often assumed in practice); and if the security price process $S$ has value $S_t = s$, then it will move up or down at the next tick $\Delta t$ to

$$s \exp(\mu \Delta t + \sigma \sqrt{\Delta t}) \quad \text{if up}$$
$$s \exp(\mu \Delta t - \sigma \sqrt{\Delta t}) \quad \text{if down}$$

with $p$ being the probability of going up or down (here take $p = \frac{1}{2}$). Thus for a time $t$, if $n = t/\Delta t$, we get

$$S_t = S_0 \exp\left( \mu t + \sigma \sqrt{t} \left( \frac{2X_n - n}{\sqrt{n}} \right) \right),$$

where $X_n$ counts the number of jumps up. By the Central Limit Theorem $S_t$ converges, as $n$ tends to infinity, to a log normal process; that is log $S_t$ has a normal distribution with mean log($S_0 + \mu t$) and variance $\sigma^2 t$.

Next we use the absence of arbitrage to change $p$ from $\frac{1}{2}$ to $p^*$. We find $p^*$ by requiring that $E^*\{S_t\} = E^*\{S_0\}$, and we get $p^*$ approximately equal to

$$p^* = \frac{1}{2} \left( 1 - \sqrt{\Delta t} \left( \frac{\mu + \frac{1}{2} \sigma^2}{\sigma} \right) \right).$$

Thus under $P^*$, $X_n$ is still Binomial, but now it has mean $np^*$ and variance $np^*(1 - p^*)$. Therefore $(2X_n - n)/\sqrt{n}$ has mean $-\sqrt{t}(\mu + \frac{1}{2} \sigma^2)/\sigma$ and a variance which converges
to 1 asymptotically. The Central Limit Theorem now implies that $S_t$ converges as $n$ tends to infinity to a log normal distribution: $\log S_t$ has mean $\log S_0 - \frac{1}{2} \sigma^2 t$ and variance $\sigma^2 t$. Thus

$$S_t = S_0 \exp(\sigma \sqrt{t} Z - \frac{1}{2} \sigma^2 t)$$

where $Z$ is $N(0,1)$ under $P^*$. This is known as the “binomial approximation” approach. A more detailed treatment can be found in Section I.1.e of Shiryaev (1999). The binomial approximation methods can be further used to derive the Black–Scholes equations, by taking limits, leading to simple formulas in the continuous case. (We present these formulas in Section 3.9). It is originally due to Cox et al. (1979), and a nice exposition can be found in Section 11B of Duffie (1996), or alternatively in Section 2.1.2 of Musiela and Rutkowski (1997).

3. Basic definitions

Throughout this section we will assume that we are given an underlying probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, P)$. We further assume $\mathcal{F}_s \subset \mathcal{F}_t$ if $s < t$; $\mathcal{F}_0$ contains all the $P$-null sets of $\mathcal{F}$; and also that $\bigcap_{s \geq t} \mathcal{F}_s = \mathcal{F}_t$ by hypothesis. This last property is called the right continuity of the filtration. These hypotheses, taken together, are known as the usual hypotheses. (When the usual hypotheses hold, one knows that every martingale has a version which is càdlàg, one of the most important consequences of these hypotheses.)

3.1. The price process

We let $S = (S_t)_{t \geq 0}$ be a semimartingale which will be the price process of a risky security. A trading strategy is a predictable process $H = (H_t)_{t \geq 0}$; its economic interpretation is that at time $t$ one holds an amount $H_t$ of the asset. Often one has concrete situations that $H$ is adapted and càdlàg (left continuous with right limits). (Indeed, it is difficult to imagine a practical trading strategy with pathological path irregularities.) In the case $H$ is adapted and càdlàg, then

$$\int_0^t H_t \, dS_t = \lim_{n \to \infty} \sum_{t \in \pi^n[0,t]} H_t \Delta_s$$

where $\pi^n[0,t]$ is a sequence of partitions of $[0,t]$ with mesh tending to 0 as $n \to \infty$; $\Delta_s S = S_{s+1} - S_s$; and with convergence in u.c.p. (uniform in time on compacts and converging in probability). Thus inspired by (5) we let

$$G_t = \int_0^t H_t \, dS_t$$

and $G$ is called the (financial) gain process generated by $H$. 

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Footnote: One definition of a semimartingale is a process $S$ that has a decomposition $S = M + A$, with $M$ a local martingale and $A$ an adapted process with càdlàg paths of finite variation on compacts. See Protter (1990) for all information regarding semimartingales.
3.2. Interest rates

Let \( r \) be a fixed rate of interest. If one invests \( D \) dollars at rate \( r \) for one year, at the end of the year one has \( D + rD = D(1 + r) \). If interest is paid at \( n \) evenly spaced times during the year and compounded, then at the end of the year one has \( D(1 + r/n)^n \). This leads us to the notion of an interest rate \( r \) compounded continuously:

\[
\lim_{n \to \infty} D \left(1 + \frac{r}{n}\right)^n = De^r
\]

or, for a fraction \( t \) of the year, one has \( D e^{rt} \) after \( t \) units of time for an interest rate \( r \) compounded continuously. We define

\[
R(t) = De^{rt};
\]

then \( R \) satisfies the ODE (ODE abbreviates Ordinary Differential Equation)

\[
dR(t) = rR(t)dt; \quad R(0) = D. \tag{6}
\]

Using the ODE(6) as a basis for interest rates, one can treat a variable interest rate \( r(t) \) as follows: (\( r(t) \) can be random; that is \( r(t) = r(t, \omega) \)):

\[
dR(t) = r(t)R(t)dt; \quad R(0) = D \tag{7}
\]

and solving yields \( R(t) = D \exp(\int_0^t r(s)ds) \). We think of the interest rate process \( R(t) \) as the price of a risk-free bond. It is perhaps more accurate to call \( R(t) \) the price of a risk free savings account to avoid confusion with other uses of the word bond. However we nevertheless keep with the use of “bond” in this article.

3.3. Portfolios

We will assume as given a risky asset with price process \( S \) and a risk-free bond with price process \( R \). Let \((a_t)_{t \geq 0}\) and \((b_t)_{t \geq 0}\) be our trading strategies for the security and the bond, respectively.

We call our holdings of \( S \) and \( R \) our portfolio.

Definition. The value at time \( t \) of a portfolio \((a, b)\) is

\[
V_t(a, b) = a_tS_t + b_tR_t. \tag{8}
\]

Now we have our first problem. Later we will want to change probabilities so that \( V = (V_t(a, b))_{t \geq 0} \) is a martingale. One usually takes the right continuous versions of martingales, so we will want the right side of (8) to be at least càdlàg. Typically this is not a real problem. Even if the process \( a \) has no regularity, one can always choose \( b \) in such a way that \( V_t(a, b) \) is càdlàg.

Let us next define two sigma algebras on the product space \( \mathbb{R}_+ \times \Omega \). We recall we are given an underlying probability space \((\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, P)\) satisfying the “usual hypotheses.”

Definition. Let \( \mathcal{L} \) denote the space of left continuous processes whose paths have right limits (càglàd), and which are adapted: that is, \( H_t \in \mathcal{F}_t \), for \( t \geq 0 \). The predictable
The optional \( \mathcal{O} \)-algebra on \( \mathbb{R}_+ \times \Omega \) is
\[
\mathcal{O} = \sigma\{H: H \text{ is càdlàg and adapted}\}.
\]
That is \( \mathcal{O} \) is the smallest \( \sigma \)-algebra that makes all of \( L \) measurable.

**Definition.** The optional \( \sigma \)-algebra \( \mathcal{O} \)-algebra on \( \mathbb{R}_+ \times \Omega \) is
\[
\mathcal{O} = \sigma\{H: H \text{ is càdlàg and adapted}\}.
\]

In general we have \( \mathcal{P} \subset \mathcal{C} \); in the case where \( B=\{B_t\}_{t \geq 0} \) is a standard Wiener process (or “Brownian motion”), and \( \mathcal{F}_t^0 = \sigma(B_s; s \leq t) \) and \( \mathcal{F}_t = \mathcal{F}_t^0 \vee \mathcal{N} \) where \( \mathcal{N} \) are the \( P \)-null sets of \( \mathcal{F} \), then we have \( \mathcal{C} = \mathcal{P} \). In general \( \mathcal{C} \) and \( \mathcal{P} \) are not equal. Indeed if they are equal, then every stopping time is predictable: that is, there are no totally inaccessible stopping times.\(^3\) Since the jump times of (reasonable) Markov processes are totally inaccessible, any model which contains a Markov process with jumps (such as a Poisson Process) will have \( \mathcal{P} \subset \mathcal{C} \), where the inclusion is strict.

**Side Remark on filtration issues:** The predictable \( \sigma \)-algebra \( \mathcal{P} \) is important because it is the natural \( \sigma \)-field for which stochastic integrals are defined. In the special case of Brownian motion one can use the optional \( \sigma \)-algebra (since they are the same). There is a third \( \sigma \)-algebra which is often used, known as the progressively measurable sets, and denoted \( \pi \). One has, in general, that \( \mathcal{P} \subset \mathcal{C} \subset \pi \); however in practice one gains very little by assuming a process is \( \pi \)-measurable instead of optional, if — as is the case here — one assumes that the filtration \( \{\mathcal{F}_t\}_{t \geq 0} \) is right continuous (i.e. \( \mathcal{F}_{t+} = \mathcal{F}_t \), all \( t \geq 0 \)). The reason is that the primary use of \( \pi \) is to show that adapted, right-continuous processes are \( \pi \)-measurable and in particular that \( X_T \in \mathcal{F}_T \) for \( T \) a stopping time and \( X \) progressive; but such processes are already optional if \( \{\mathcal{F}_t\}_{t \geq 0} \) is right continuous. Thus there are essentially no “naturally occurring” examples of progressively measurable processes that are not already optional. An example of such a process, however, is the indicator function \( 1_G(t) \), where \( G \) is described as follows: let \( Z = \{(t, \omega): B_t(\omega) = 0\} \). (\( B \) is standard Brownian motion.) Then \( Z \) is a perfect (and closed) set on \( \mathbb{R}_+ \) for almost all \( \omega \). For fixed \( \omega \), the complement is an open set and hence a countable union of open intervals. \( G(\omega) \) denotes the left end-points of these open intervals. One can then show (using the Markov property of \( B \) and P. A. Meyer’s section theorems) that \( G \) is progressively measurable but not optional. In this case note that \( 1_G(t) \) is zero except for countably many \( t \) for each \( \omega \), hence

\(^3\) A **totally inaccessible stopping time** is a stopping time that comes with no advance warning: it is a complete surprise. A stopping time \( T \) is **totally inaccessible** if whenever there exists a sequence of non-decreasing stopping times \( \{S_n\}_{n \geq 1} \) with \( A = \bigcap_{n=1}^{\infty} \{S_n < T\} \), then
\[
P(\{w: \lim S_n = T \} \cap A) = 0.
\]
A stopping time \( T \) is **predictable** if there exists a non-decreasing sequence of stopping times \( \{S_n\}_{n \geq 1} \) as above with
\[
P(\{w: \lim S_n = T \} \cap A) = 1.
\]
Note that the probabilities above need not be only 0 or 1; thus there are in general stopping times which are neither predictable nor totally inaccessible.
\[ \int 1_G(s) \, dB_s = 0. \] Finally we note that if \( a = (a_s)_{s \geq 0} \) is progressively measurable, then 
\[ \int_0^t a_s \, dB_s = \int_0^t \hat{a}_s \, dB_s, \] 
where \( \hat{a} \) is the predictable projection of \( a \).

Let us now recall a few details of stochastic integration. First, let \( S \) and \( X \) be any two càdlàg semimartingales. The integration by parts formula can be used to define the quadratic co-variation of \( X \) and \( S \):

\[ [X, S]_t = X_t Y_t - \int_0^t X_s \, dS_s - \int_0^t S_s \, dX_s. \]

However if a càdlàg, adapted process \( H \) is not a semimartingale, one can still give the quadratic co-variation a meaning, by using a limit in probability as the definition. This limits always exists if both \( H \) and \( S \) are semimartingales:

\[ [H, S]_t = \lim_{n \to \infty} \sum_{t_i \in \pi^n[0,t]} (H_{t_{i+1}} - H_{t_i})(S_{t_{i+1}} - S_t) \]

where \( \pi^n[0,t] \) be a sequence of finite partitions of \([0,t]\) with \( \lim_{n \to \infty} \text{mesh}(\pi^n) = 0 \).

Henceforth let \( S \) be a (càdlàg) semimartingale, and let \( H \) be càdlàg and adapted, or alternatively \( H \in \mathbb{L} \). Let \( H_- = (H_{t-})_{t \geq 0} \) denote the left-continuous version of \( H \). (If \( H \in \mathbb{L} \), then of course \( H = H_- \).) We have:

**Theorem.** \( H \) càdlàg, adapted or \( H \in \mathbb{L} \). Then

\[ \lim_{n \to \infty} \sum_{t_i \in \pi^n[0,t]} H_t(S_{t_{i+1}} - S_t) = \int_0^t H_s \, dS_s, \]

with convergence uniform in \( s \) on \([0,t]\) in probability.

We remark that it is crucial that we sample \( H \) at the left endpoint of the interval \([t_i, t_{i+1}]\). Were we to sample at, say, the right endpoint or the midpoint, then the sums would not converge in general (they converge for example if the quadratic covariation process \([H, S]\) exists); in cases where they do converge, the limit is in general different. Thus while the above theorem gives a pleasing “limit as Riemann sums” interpretation to a stochastic integral, it is not at all a perfect analogy.

The basic idea of the preceding theorem can be extended to bounded predictable processes in a method analogous to the definition of the Lebesgue integral for real-valued functions. Note that

\[ \sum_{t_i \in \pi^n[0,t]} H_t(S_{t_{i+1}} - S_t) = \int_0^t H^n_s \, dS_s, \]

where \( H^n_t = \sum H_t 1_{(t_i, t_{i+1}]} \) which is in \( \mathbb{L} \); thus these “simple” processes are the building blocks, and since \( \sigma(\mathbb{L}) = \mathcal{P} \), it is unreasonable to expect to go beyond \( \mathcal{P} \) when defining the stochastic integral.

---

4Let \( H \) be a bounded, measurable process. \( (H \) need not be adapted.) The **predictable projection** of \( H \) is the unique predictable process \( \hat{H} \) such that

\[ \hat{H}_T = \mathbb{E}(H|\mathcal{F}_T-) \quad \text{a.s. on } \{ T < \infty \} \]

for all predictable stopping times \( T \). Here \( \mathcal{F}_T- = \sigma\{ A \cap \{ t < T \}; A \in \mathcal{F} \} \cup \mathcal{F}_0 \). For a proof of the existence and uniqueness of \( \hat{H} \) see (Protter, 1990, p. 119).
There is, of course, a maximal space of integrable processes where the stochastic integral is well defined and still gives rise to a semimartingale as the integrated process; without describing it (see any book on stochastic integration such as Protter (1990)), we define:

**Definition.** For a semimartingale \( S \) we let \( L(S) \) denote the space of predictable processes \( a \), where \( a \) is integrable with respect to \( S \).

We would like to fix the underlying semimartingale (or vector of semimartingales) \( S \). The process \( S \) represents the price process of our risky asset. A way to do that is to introduce the notion of a model. We present two versions. The first is the more complete, as it specifies the probability space and the underlying filtration. However it is also cumbersome, and thus we will abbreviate it with the second:

**Definition.** A sextuple \((\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, S, L(S), P)\) is called an asset pricing model; or more simply, the triple \((S, L(S), P)\) is called a model, where the probability space and \( \sigma \)-algebras are implicit: that is, \((\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0})\) is implicit.

We are now ready for a key definition.

**Definition.** A strategy \((a, b)\) is called self-financing if \( a \in L(S) \), \( b \) is optional and \( b \in L(R) \), and

\[
a_t S_t + b_t R_t = a_0 S_0 + b_0 R_0 + \int_0^t a_s dS_s + \int_0^t b_s dR_s
\]

for all \( t \geq 0 \).

Note that Eq. (9) above implies that \( a_t S_t + b_t R_t \) is càdlàg. We also remark that it is reasonable that \( a \) be predictable: \( a \) is the trader’s holdings at time \( t \), and this is based on information obtained at times strictly before \( t \), but not \( t \) itself.

We remark that for simplicity we are assuming we have only one risky asset.

The next concept is of fundamental importance. An arbitrage opportunity is the chance to make a profit without risk. One way to model that mathematically is as follows:

**Definition.** A model is arbitrage free if there does not exist a self-financing strategy \((a, b)\) such that \( V_0(a, b) = 0 \), \( V_T(a, b) \geq 0 \), and \( P(V_T(a, b) > 0) > 0 \).

### 3.4. Equivalent martingale measures

Let \( S = (S_t)_{0 \leq t \leq T} \) be our risky asset price process, which we are assuming is a semimartingale. Moreover we will assume in this subsection that the price \( R(t) \) of a risk free bond is constant and equal to one. That is, \( r(t) = 0 \), all \( t \). Let

\[
S_t = S_0 + M_t + A_t
\]
be a semimartingale decomposition of \( S \); \( M \) is a local martingale and \( A \) is an adapted càdlàg process of finite variation on compacts. We are working on a fixed and given filtered probability space \((\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, P)\).

**Definition.** A model is *good* if there exists an equivalent\(^5\) probability measure \( Q \) such that \( S \) is a \( Q \)-local martingale.

We remark that a price process \( S \) can easily not be “good”. Indeed, if \( Z = \frac{dQ}{dP} \) and \( Z_t = E_P[Z \mid \mathcal{F}_t] \), then the Meyer–Girsanov theorem gives the \( Q \) decomposition of \( S \) by

\[
S_t = \left( M_t - \int_0^t \frac{1}{Z_s} \, d[Z,M]_s \right) + \left( A_t + \int_0^t \frac{1}{Z_s} \, d[Z,M]_s \right).
\]

In order for \( S \) to be a \( Q \)-local martingale we need\(^6\) to have \( A_t = -\int_0^t (1/Z_s) \, d[Z,M]_s \).

The Kunita–Watanabe inequality implies that \( d[Z,M] \ll d[M,M] \); that is, \( \omega \) by \( \omega \) the paths of \([Z,M]\) are a.s. absolutely continuous, when considered as the measures they induce on the non-negative reals, with respect to the paths of \([M,M]\). Hence a *necessary* condition for a model to be good is that

\[
dA_t \ll d[M,M], \quad \text{a.s.}
\]

Note that this implies in particular in the Brownian case that if \( M_t = \int_0^t \theta_s \, dB_s \), then \( A_t \) must of necessity be of the form \( A_t = \int_0^t \gamma_s \theta_s^2 \, ds \) for some process \( \gamma \). This will hence eliminate some rather natural appearing processes as possible price processes. For example, by Tanaka’s formula from stochastic calculus, if \( S = |B| \), where \( B \) denotes a Brownian motion, then the process \( A = L \), where \( L \) denotes the local time at level 0 of the Brownian motion \( B \). However the local time has paths whose support is carried by the zero set of Brownian motion, which has Lebesgue measure zero a.s. (see, e.g., Protter, 1990), and thus the paths of \( L \) induce measures which are singular with respect to Lebesgue measure, contradicting the necessary condition that \( dL_t \ll dt \). We conclude that \( S_t = |B_t| \) is *not* a good model.

### 3.5. The fundamental theorem of asset pricing

In Section 2 we saw that with the “No Arbitrage” assumption, at least in the case of a very simple example, we needed to change from the “true” underlying probability measure \( P \), to an equivalent one \( P^* \). Under the assumption that \( r = 0 \), or equivalently that \( R_t = 1 \) for all \( t \), the price of a contingent claim \( H \) was not \( E\{H\} \) as one might expect, but rather \( E^*\{H\} \). (If the process \( R_t \) is not constant and equal to one, then we consider the expectation of the discounted claim \( E^*\{e^{-R_t}H\} \).) The idea that led to this price was to find a probability \( P^* \) that gave the price process \( X \) a constant expectation.

In continuous time a sufficient condition for the price process \( S = (S_t)_{t \geq 0} \) to have constant expectation is that it be a martingale. That is, if \( S \) is a martingale then the function

\[ Q \] is equivalent to \( P \) if \( Q \) and \( P \) have the same sets of probability zero.

\[ 6 \] At least in the case of continuous paths.
$t \to E\{S_t\}$ is constant. Actually this property is not far from characterizing martingales. A classic theorem from martingale theory is the following (cf. e.g., Protter, 1990):

**Theorem.** Let $S = (S_t)_{t \geq 0}$ be càdlàg and suppose $E\{S_t\} = E\{S_0\}$ for any bounded stopping time $\tau$ (and of course $E\{|S_\tau|\} < \infty$). Then $S$ is a martingale.

That is, if we require constant expectation at stopping times (instead of only at fixed times), then $S$ is a martingale. Thus the general idea can be summarized by what we call an “idea”. By that we mean that there seems to be a feeling that what follows is more or less true, and indeed it is more or less true. We will try to clarify exactly to what extent, however, it is actually true. That is, we will see that it is more less true than true. Nevertheless the idea is right; we just need to state the mathematics carefully to make the idea work.

**Idea.** Let $S$ be a price process on a given space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t > 0}, P)$. Then there is an absence of arbitrage opportunities if and only if there exists a probability $P^*$, equivalent to $P$, such that $S$ is a martingale under $P^*$.

The origins of the preceding idea can be traced back to Harrison and Kreps (1979) in 1979 for the case where $\mathcal{F}_T$ is finite, and later to Dalang et al. (1990) for the case where $\mathcal{F}_T$ is infinite, but time is discrete. Before stating a more rigorous theorem (our version is due to Delbaen and Schachermayer (1994); see also Delbaen and Schachermayer, 1998), let us examine a needed hypothesis. We need to avoid problems that arise from the classical doubling strategy. Here a player bets $1$ at a fair bet. If he wins, he stops. If he loses he next bets $2$. Whenever he wins, he stops, and his profit is $1$. If he continues to lose, he continues to play, each time doubling his bet. This strategy leads to a certain gain of $1$ without risk. However the player needs to be able to tolerate arbitrarily large losses before he might gain his certain profit. Of course no one has such infinite resources to play such a game. Mathematically one can eliminate this type of problem by requiring trading strategies to give martingales that are bounded below by a constant. Thus the player’s resources, while they can be huge, are nevertheless finite and bounded by a non-random constant. This leads to the next definition.

**Definition.** Let $\alpha > 0$, and let $S$ be a semimartingale. A predictable trading strategy $\theta$ is $\alpha$-admissible if $\theta_0 = 0$, $\int_0^t \theta_s \, dS_s \geq -\alpha$, all $t \geq 0$. $\theta$ is called admissible if there exists $\alpha > 0$ such that $\theta$ is $\alpha$-admissible.

Before we make more definitions, let us recall the basic idea. Suppose $\theta$ is admissible, self-financing, with $\theta_0 S_0 = 0$ and $\theta_T S_T \geq 0$. In the next section we will see that for our purposes here by a “change of numeraire” we can neglect the bond or “numeraire” process, so that self-financing reduces to

$$\theta_T S_T = \theta_0 S_0 + \int_0^T \theta_s \, dS_s.$$
Then if \( P^* \) exists such that \( \int_0^T \theta_t \, dS_t \) is a martingale, we have

\[
E^* \{ \theta_T S_T \} = 0 + E^* \left\{ \int_0^T \theta_t \, dS_t \right\}.
\]

In general \( \int_0^T \theta_t \, dS_t \) is only a local martingale; if we know that it is a true martingale then \( \int_0^T \theta_t \, dS_t \) is a \( P^* \) true martingale, and not just a local martingale (see the proof of the Fundamental Theorem that follows). The converse is typically harder: that is, that no arbitrage implies \( P^* \) exists. The converse is proved using a version of the Hahn–Banach theorem.

Following Delbaen and Schachermayer, we make a sequence of definitions:

\[
K_0 = \left\{ \int_0^T \theta_t \, dS_t \mid \theta \text{ is admissible and } \lim_{t \to \infty} \int_0^t \theta_s \, dS_s \text{ exists a.s.} \right\}
\]

\[
C_0 = \{ \text{all functions dominated by elements of } K_0 \}
\]

\[= K_0 - L_+^0, \text{ where } L_+^0 \text{ are positive, finite random variables.} \]

\[K = K_0 \cap L^\infty \]

\[C = C_0 \cap L^\infty \]

\[\tilde{C} = \text{the closure of } C \text{ under } L^\infty. \]

**Definition.** A semimartingale price process \( S \) satisfies

(i) the *No Arbitrage* condition if \( C \cap L^\infty_+ = \{0\} \) (this corresponds to no chance of making a profit without risk);

(ii) the *No Free Lunch with Vanishing Risk* condition (NFLVR) if \( \tilde{C} \cap L^\infty_+ = \{0\} \), where \( \tilde{C} \) is the closure of \( C \) in \( L^\infty \).

Clearly condition (ii) implies condition (i). Condition (i) is slightly too restrictive to imply the existence of an equivalent martingale measure \( P^* \). (One can construct a trading strategy of \( H_t(\omega) = 1_{[0,1]}(\Omega) (t, \omega) \), which means one sells before each rational time and buys back immediately after it; combining \( H \) with a specially constructed càdlàg semimartingale shows that (i) does not imply the existence of \( P^* \)-see (Delbaen and Schachermayer, 1994, p. 511).

Let us examine then condition (ii). If NFLVR is not satisfied then there exists an \( f_0 \in L^\infty_+ \), \( f_0 \neq 0 \), and also a sequence \( f_n \in C \) such that \( \lim_{n \to \infty} f_n = f_0 \) a.s., such that for each \( n \), \( f_n \geq f_0 - 1/n \). In particular \( f_n \geq -1/n \). This is almost the same as an arbitrage opportunity, as the risk of the trading strategies becomes arbitrary small.

**Fundamental Theorem.** Let \( S \) be a bounded semimartingale. There exists an equivalent martingale measure \( P^* \) for \( S \) if and only if \( S \) satisfies NFLVR.
Proof. Let us assume we have NFLVR. Since $S$ satisfies the no arbitrage property we have $C \cap L^\infty_\infty = \{0\}$. However one can use the property NFLVR to show $C$ is weak* closed in $L^\infty$ (that is, it is closed in $\sigma(L^1, L^\infty)$), and hence there will exist a probability $P^*$ equivalent to $P$ with $E^*[f] \leq 0$, all $f$ in C. (This is the Kreps–Yan separation theorem — essentially the Hahn–Banach theorem; see, e.g., Yan, 1980). For each $s < t, B \in \mathcal{F}_s, \alpha \in \mathbb{R}$, we deduce $\alpha(S_t - S_s)1_B \in C$, since $S$ is bounded. Therefore

$$E^*[\alpha(S_t - S_s)1_B] = 0,$$

and $S$ is a martingale under $P^*$.

For the converse, note that NFLVR remains unchanged with an equivalent probability, so without loss of generality we may assume $S$ is a Martingale under $P$ itself. If $\theta$ is admissible, then $(\int_0^\infty \theta, dS_s)_{\geq 0}$ is a local martingale, hence it is a supermartingale. Since $E\{\theta_0S_0\} = 0$, we have as well $E\{\int_0^\infty \theta, dS_s\} \leq E\{\theta_0S_0\} = 0$. This implies that for any $f \in C$, we have $E\{f\} \leq 0$. Therefore it is true as well for $f \in \tilde{C}$, the closure of $C$ in $L^\infty$. Thus we conclude $C \cap L^\infty_\infty = \{0\}$. □

Corollary. Let $S$ be a locally bounded semimartingale. There is an equivalent probability measure $P^*$ under which $S$ is a local martingale if and only if $S$ satisfies NFLVR.

The measure $P^*$ in the corollary is known as a local martingale measure. We refer to Delbaen and Schachermayer (1994, p. 479) for the proof of the corollary. Examples show that in general $P^*$ can make $S$ only a local martingale, not a martingale. We also note that any semimartingale with continuous paths is locally bounded. However in the continuous case there is a considerable simplification: the No Arbitrage property alone, properly interpreted, implies the existence of an equivalent local martingale measure $P^*$ (see Delbaen and Schachermayer, 1995). Indeed using the Girsanov theorem this implies that under the No Arbitrage assumption the semimartingale must have the form

$$S_t = M_t + \int_0^t h_s d[M, M],$$

where $M$ is a local martingale under $P$, and with restrictions on the predictable process $h$. Indeed, if one has $\int_0^\infty h_t^2 d[M, M] < \infty$ for some $\varepsilon > 0$, then $S$ admits “immediate arbitrage”, a fascinating concept introduced by Delbaen and Schachermayer (see Delbaen and Schachermayer, 1995). Last, one can consult Delbaen and Schachermayer, 1998 for results on unbounded $S$.

3.6. Normalizing the bond price

Our Portfolio as described in Section 3.3 consists of

$$V_t(a, b) = a S_t + b R_t,$$

where $(a, b)$ are trading strategies, $S$ is the risky security price, and $R_t = D \exp(\int_0^t r_s ds)$ is the price of a risk-free bond. The process $R$ is often called a numeraire. One often takes $D = 1$ and then $R_t$ represents the time value of money. One can then deflate future monetary values by multiplying by $1/R_t = \exp(- \int_0^t r_s ds)$. Let us write $Y_t = 1/R_t$ and we shall refer to the process $Y_t$ as a deflator. By multiplying $S$ and $R$ by $Y = 1/R$, we get

$$V_t(a, b) = a Y S_t + b Y R_t.$$
we can effectively reduce the situation to the case where the price of a risk free bond is constant and equal to one. The next theorem allows us to do that.

**Theorem (Numeraire invariance).** Let \((a,b)\) be a strategy for \((S,R)\). Let \(Y = 1/R\). Then \((a,b)\) is self-financing for \((S,R)\) if and only if \((a,b)\) is self-financing for \((YS,1)\).

**Proof.** Let \(Z = \int_0^t a_s \, dS_s + \int_0^t b_s \, dR_s\). Then using integration by parts we have (since \(Y\) is continuous and of finite variation)

\[
d(Y_t Z_t) = Y_t \, dZ_t + Z_t \, dY_t \\
= Y_t a_t \, dS_t + Y_t b_t \, dR_t + \left( \int_0^t a_s \, dS_s + \int_0^t b_s \, dR_s \right) \, dY_t \\
= a_t (Y_t \, dS_t + S_t \, dY_t) + b_t (Y_t \, dR_t + R_t \, dY_t) \\
= a_t \, d(YS)_t + b_t \, d(YR)_t \\
and since \(YR = (1/R)R = 1\), this is \\
= a_t \, d(YS)_t
\]

since \(dYR = 0\) because \(YR\) is constant. Therefore

\[
a_t S_t + b_t R_t = a_0 S_0 + b_0 + \int_0^t a_s \, dS_s + \int_0^t b_s \, dR_s \\
if and only if \\
a_t \frac{1}{R_t} S_t + b_t = a_0 S_0 + b_0 + \int_0^t a_s \, d \left( \frac{1}{R} S \right)_s.
\]

The Numeraire Invariance Theorem allows us to assume \(R \equiv 1\) without loss of generality. Note that one can check as well that there is no arbitrage for \((a,b)\) with \((S,R)\) if and only if there is no arbitrage for \((a,b)\) with \((1/R)S,1\). By renormalizing, we no longer write \((1/R)S,1\), but simply \(S\).

The preceding theorem is the standard version, but in many applications (for example those arising in the modeling of interest rates), one wants to assume that the numeraire is a strictly positive semimartingale (instead of only a continuous finite variation process as in the previous theorem). We consider here the general case, where the numeraire is a (not necessarily continuous) semimartingale. For examples of how such a change of numeraire theorem can be used (albeit for the case where the deflator is assumed continuous), see for example (Geman et al., 1995). A reference to the literature for a result such as the following theorem is (Huang, 1985, p. 223).

**Theorem (Numeraire invariance; general case).** Let \(S, R\) be semimartingales, and assume \(R\) is strictly positive. Then the deflator \(Y = 1/R\) is a semimartingale and \((a,b)\) is self-financing for \((S,R)\) if and only if \((a,b)\) is self-financing for \((\frac{S}{R},1)\).
Proof. Since \( f(x) = 1/x \) is \( C^2 \) on \((0, \infty)\), we have that \( Y \) is a (strictly positive) semimartingale by Itô’s formula. By the self-financing hypothesis we have

\[
V_t(a, b) = a_t S_t + b_t R_t
\]

\[
= a_0 S_0 + b_0 R_0 + \int_0^t a_s \, dS_s + \int_0^t b_s \, dR_s.
\]

Let us assume \( S_0 = 0 \), and \( R_0 = 1 \). The integration by parts formula for semimartingales gives

\[
d(S_t Y_t) = d \left( \frac{S_t}{R_t} \right) = S_t \, d \left( \frac{1}{R_t} \right) + \frac{1}{R_t} \, dS_t + d \left[ S_t, \frac{1}{R_t} \right],
\]

and

\[
d \left( \frac{V_t}{R_t} \right) = V_t \, d \left( \frac{1}{R_t} \right) + \frac{1}{R_t} \, dV_t + d \left[ V_t, \frac{1}{R_t} \right].
\]

We can next use the self-financing assumption to write:

\[
d \left( \frac{V_t}{R_t} \right) = a_t S_t \, d \left( \frac{1}{R_t} \right) + b_t R_t \, d \left( \frac{1}{R_t} \right) + \frac{1}{R_t} \, a_t dS_t + \frac{1}{R_t} \, b_t dR_t
\]

\[
+ a_t \left[ S_t, \frac{1}{R_t} \right] + b_t \left[ R_t, \frac{1}{R_t} \right],
\]

\[
= a_t \left( S_t \, d \left( \frac{1}{R} \right) + \frac{1}{R} \, dS + d \left[ S, \frac{1}{R} \right] \right)
\]

\[
+ b_t \left( R_t \, d \left( \frac{1}{R} \right) + \frac{1}{R} \, dR + d \left[ R, \frac{1}{R} \right] \right)
\]

\[
= a_t d \left( \frac{1}{R} \right) + b_t d \left( \frac{R}{R} \right).
\]

Of course \( R_t(1/R_t) = 1 \), and \( d(1) = 0 \); hence

\[
d \left( \frac{V_t}{R_t} \right) = a_t d \left( \frac{1}{R_t} \right).
\]

In conclusion we have

\[
V_t = a_t S_t + b_t R_t = b_0 + \int_0^t a_s \, dS_s + \int_0^t b_s \, dR_s,
\]

and

\[
a_t \left( \frac{S_t}{R_t} \right) + b_t = \frac{V_t}{R_t} = b_0 + \int_0^t a_s \, d \left( \frac{S_t}{R_t} \right). \quad \square
\]

3.7. Redundant claims

Let us assume given a security price process \( S_t \), and by the results in Section 3.6 we take \( R_t \equiv 1 \). Let \( \mathcal{F}_t^0 = \sigma(S_r; r \leq t) \) and let \( \mathcal{F}_t^\sim = \mathcal{F}_t^0 \vee \mathcal{N} \) where \( \mathcal{N} \) are the null sets of \( \mathcal{F} \) and \( \mathcal{F} = \bigvee_t \mathcal{F}_t^0 \), under \( P \), defined on \((\Omega, \mathcal{F}, P)\). Finally we take \( \mathcal{F}_t = \bigcap_{u>t} \mathcal{F}_u^\sim \).
A contingent claim on $S$ is then a random variable $H \in \mathcal{F}_T$, for some fixed time $T$. Note that we pay a small price here for the simplification of taking $R_t \equiv 1$, since if $R_t$ were to be a nonconstant stochastic process, it might well change the minimal filtration we are taking, because then the processes of interest would be $(R_t, S_t)$, in place of just $e^{-R_t S_t}$. One goal of Finance Theory is to show there exists a trading strategy $(a, b)$ that one can use either to obtain $H$ at time $T$, or to come as close as possible — in an appropriate sense — to obtaining $H$.

**Definition.** Let $S$ be the price process of a risky security and let $R$ be the price process of a risk free bond (numeraire), which we will be setting equal to the constant process $1$. A contingent claim $H \in \mathcal{F}_T$ is said to be redundant if there exists an admissible self-financing strategy $(a, b)$ such that

$$H = a_0 S_0 + b_0 R_0 + \int_0^T a_s dS_s + \int_0^T b_s dR_s.$$  

Let us normalize $S$ by writing $M = (1/R) S$; then $H$ will still be redundant under $M$ and hence we have (taking $R_t = 1$, all $t$):

$$H = a_0 M_0 + b_0 + \int_0^T a_s dM_s.$$  

Next note that if $P^*$ is any equivalent martingale measure making $M$ a martingale, and if $H$ has finite expectation under $P^*$, we then have

$$E^*\{H\} = E^*\{a_0 M_0 + b_0\} + E^*\left\{\int_0^T a_s dM_s\right\}$$  

provided all expectations exist,

$$= E^*\{a_0 M_0 + b_0\} + 0.$$  

**Theorem.** Let $H$ be a redundant contingent claim such that there exists an equivalent martingale measure $P^*$ with $H \in \mathcal{L}^*(M)$. (See the second definition following for a definition of $\mathcal{L}^*(M)$). Then there exists a unique no arbitrage price of $H$ and it is $E^*\{H\}$.

**Proof.** First we note that the quantity $E^*\{H\}$ is the same for every equivalent martingale measure. Indeed if $Q_1$ and $Q_2$ are both equivalent martingale measures, then

$$E_{Q_1}\{H\} = E_{Q_1}\{a_0 M_0 + b_0\} + E_{Q_1}\left\{\int_0^T a_s dM_s\right\}.$$  

But $E_{Q_1}\left\{\int_0^T a_s dM_s\right\} = 0$, and $E_{Q_2}\{a_0 M_0 + b_0\} = a_0 M_0 + b_0$, since we assume $a_0$, $M_0$, and $b_0$ are known at time 0 and thus without loss of generality are taken to be constants.

Next suppose one offers a price $\pi > E^*\{H\} = a_0 M_0 + b_0$. Then one follows the strategy $a = (a_s)_{s \geq 0}$ and (we are ignoring transaction costs) at time $T$ one has $H$ to present to the purchaser of the option. One thus has a sure profit (that is, risk free)

---

$^7$Although $R$ is taken to be constant and equal to 1, we include it initially in the definition to illustrate the role played by being able to take it a constant process.
of $\pi - (a_0 M_0 + b_0) > 0$. This is an arbitrage opportunity. On the other hand if one can buy the claim $H$ at a price $\pi < a_0 M_0 + b_0$, analogously at time $T$ one will have achieved a risk-free profit of $(a_0 M_0 + b_0) - \pi$. $\square$

**Definition.** If $H$ is a redundant claim, then there exists an admissible self-financing strategy $(a, b)$ such that

$$H = a_0 M_0 + b_0 + \int_0^T a_s \, dM_s,$$

the strategy $a$ is said to replicate the claim $H$.

**Corollary.** If $H$ is a redundant claim, then one can replicate $H$ in a self-financing manner with initial capital equal to $E^*\{H\}$, where $P^*$ is any equivalent martingale measure for the normalized price process $M$.

At this point we return to the issue of put–call parity mentioned in the introduction (Section 2). Recall that we had the trivial relation

$$M_T - K = (M_T - K)^+ - (K - M_T)^+,$$

which, by taking expectations under $P^*$, shows that the price of a call at time $0$ equals the price of a put minus $K$. More generally at time $t$, $E^*\{(M_T - K)^+ | \mathcal{F}_t\}$ equals the value of a put at time $t$ minus $K$, by the $P^*$ martingale property of $M$.

It is tempting to consider markets where all contingent claims are redundant. Unfortunately this is too large a space of random variables; we wish to restrict ourselves to claims that have good integrability properties.

Let us fix an equivalent martingale measure $P^*$, so that $M$ is a martingale (or even a local martingale) under $P^*$. We consider all self-financing strategies $(a, b)$ such that the process $\left(\int_0^T a_s^2 \, d[M,M]_s\right)^{1/2}$ is locally integrable: that means that there exists a sequence of stopping times $(T_n)_{n \geq 1}$ which can be taken $T_n \leq T_{n+1}$, a.s., such that $\lim_{n \to \infty} T_n \geq T$ a.s. and $E^*\left\{\left(\int_0^T a_s^2 \, d[M,M]_s\right)^{1/2}\right\} < \infty$, each $T_n$. Let $\mathcal{L}^*(M)$ denote the class of such strategies, under $P^*$. We remark that we are cheating a little here: we are letting our definition of a complete market (which follows) depend on the measure $P^*$, and it would be preferable to define it in terms of the objective probability $P$. How to go about doing this is a much discussed issue. In the happy case where the price process is already a local martingale under the objective probability measure, this issue of course disappears.

Recall that market models are defined in Section 3.3.

**Definition.** A market model $(M, \mathcal{L}^*(M), P^*)$ is complete if every claim $H \in L^1(\mathcal{F}_T, dP^*)$ is redundant for $\mathcal{L}^*(M)$. That is for any $H \in L^1(\mathcal{F}_T, dP^*)$, there exists an admissible self-financing strategy $(a, b)$ with $a \in \mathcal{L}^*(M)$ such that

$$H = a_0 M_0 + b_0 + \int_0^T a_s \, dM_s,$$

and such that $\left(\int_0^T a_s^2 \, dM_s\right)_{t \geq 0}$ is uniformly integrable. In essence, then, a complete market is one for which every claim is redundant.
We point out that the above definition is one of many possible definitions of a complete market. For example one could limit attention to nonnegative claims, and/or claims that are in $L^2(\mathcal{F}_T, dP^*)$; one could as well alter the definition of a redundant claim.

We note that in probability theory a martingale $M$ is said to have the predictable representation property if for any $H \in L^2(\mathcal{F}_T)$ one has

$$H = E\{H\} + \int_0^T a_s \, dM_s$$

for some predictable $a \in \mathcal{L}(M)$. This is of course essentially the property of market completeness. Martingales with predictable representation are well studied and this theory can usefully be applied to Finance. For example suppose we have a good model $(S, R)$ where by a change of numéraire we can take $R = 1$. Suppose further there is an equivalent martingale measure $P^*$ such that $S$ is a Brownian motion under $P^*$. Then the model is complete for all claims $H$ in $L^1(\mathcal{F}_T, dP^*)$ such that $H \geq -\alpha$, for some $\alpha > 0$. (This can depend on $H$.) To see this, we use martingale representation (see, e.g., Protter, 1990, p. 156) to find a predictable process $a$ such that for $0 \leq t \leq T$:

$$E^*\{H|\mathcal{F}_t\} = E^*\{H\} + \int_0^t a_s \, dS_s.$$

Let

$$V_t(a, b) = a_0S_0 + b_0 + \int_0^t a_s \, dS_s + \int_0^t b_s \, dR_s;$$

we need to find $b$ such that $(a, b)$ is an admissible, self-financing strategy. Since $R_t = 1$, we have $dR_t = 0$, hence we need

$$a_tS_t + b_tR_t = b_0 + \int_0^t a_s \, dS_s;$$

and taking $b_0 = E^*\{H\}$, we have

$$b_t = b_0 + \int_0^t a_s \, dS_s - a_tS_t;$$

provides such a strategy. It is admissible since $\int_0^t a_s \, dS_s \geq -\alpha$ for some $\alpha$ which depends on $H$.

Unfortunately having the predictable representation property is rather delicate, and few martingales possess this property. Examples include Brownian motion, the Compensated Poisson process (but not mixtures of the two nor even the difference of two Poisson processes), and the Azéma martingales. (One can consult Dritschel and Protter (1999) and also Jeanblanc and Privault (2000) for more on the Azéma martingales.)

One can mimic a complete market in the case (for example) of two independent noises, each of which is complete alone. Several authors have done this with Brownian noise together with compensated Poisson noise, by proposing hedging strategies for each noise separately. A recent example of this is Kusuoka (1999) (where the Poisson intensity can depend on the Brownian motion) in the context of default risk models. A more traditional example is Jeanblanc-Piqué and Pontier (1990).
Most models are therefore not complete, and most practitioners believe the actual financial world being modeled is not complete. We have the following result:

**Theorem.** There is a unique $P^*$ such that $M$ is a local martingale only if the market is complete.

This theorem is a trivial consequence of Dellacherie’s approach to Martingale Representation: if there is a unique probability making a process $M$ a local martingale, then $M$ must have the martingale representation property. The theory has been completely resolved in the work of Jacod and Yor. To give an example of what can happen, let $\mathcal{M}^2$ be the set of equivalent probabilities making $M$ an $L^2$-martingale. Then $M$ has the predictable representation property (and hence market completeness) for every extremal element of the convex set $\mathcal{M}^2$. If $\mathcal{M}^2 = \{P^*\}$, only one element, then of course $P^*$ is extremal. (See Protter, 1990, p. 152.) Indeed $P^*$ is in fact unique in the proto-typical example of Brownian motion; since many diffusions can be constructed as pathwise functionals of Brownian motion they inherit the completeness of the Brownian model. But there are examples where one has complete markets without the uniqueness of the equivalent martingale measure (see Artzner and Heath (1995) in this regard, as well as Jarrow et al. (1999)). Nevertheless the situation is simpler when we assume our models have continuous paths. The next theorem is a version of what is known as the second fundamental theorem of asset pricing. We state and prove it for the case of $L^2$ claims only. We note that this theorem has a long and illustrious history, going back to the fundamental paper of Harrison and Kreps (1979, p. 392) for the discrete case, and to Harrison and Pliska (1981, p. 241) for the continuous case, although in Harrison and Pliska (1981) the theorem below is stated only for the “only if” direction.

**Theorem.** Let $M$ have continuous paths. There is a unique $P^*$ such that $M$ is an $L^2$ $P^*$-martingale if and only if the market is complete.

**Proof.** The theorem follows easily from Theorems 37–39 of Protter (1990, p. 152); we will assume those results and prove the theorem. Theorem 39 shows that if $P^*$ is unique then the market model is complete. If $P^*$ is not unique but the model is nevertheless complete, then by Theorem 37 $P^*$ is nevertheless extremal in the space of probability measures making $M$ an $L^2$ martingale. Let $Q$ be another such extremal probability, and let $L_\infty = dQ/dP^*$ and $L_t = E_P\{L_\infty|\mathcal{F}_t\}$, with $L_0 = 1$. Let $T_n = \inf\{t > 0: |L_t| \geq n\}$. $L$ will be continuous by Theorem 39 (Protter, 1990, p. 152), hence $L^n_t = L_{t\wedge T_n}$ is bounded. We then have, for bounded $H \in \mathcal{F}$:

\[
E_Q\{M_{t\wedge T_n}H\} = E^*\{M_{t\wedge T_n}L^n_t H\},
\]

\[
E_Q\{M_{t\wedge T_n}H\} = E^*\{M_{t\wedge T_n}L^n_t H\}.
\]

The two left sides of the above equalities are equal and this implies that $ML^n_t$ is a martingale, and thus $L^n_t$ is a bounded $P^*$-martingale orthogonal to $M$. It is hence constant by Theorem 38. We conclude $L_\infty \equiv 1$ and thus $Q = P^*$. ❑
Note that if \( H \) is a redundant claim, then the no arbitrage price of \( H \) is \( E^{*}\{H\} \), for any equivalent martingale measure \( P^{*} \). (If \( H \) is redundant then we have seen the quantity \( E^{*}\{H\} \) is the same under every \( P^{*} \).) However, if a “good” market model is not complete, then

(i) there will arise nonredundant claims,
(ii) there will be more than one equivalent martingale measure \( P^{*} \).

We now have the conundrum: if \( H \) is nonredundant, what is the no arbitrage price of \( H \)? We can no longer argue that it is \( E^{*}\{H\} \), because there are many such values!

The absence of this conundrum is a large part of the appeal of complete markets.

Finally let us note that when \( H \) is redundant there is always a replication strategy \( a \). However, when \( H \) is nonredundant it cannot be replicated; in this event we do the best we can in some appropriate sense (for example expected squared error loss), and we call the strategy we follow a hedging strategy. See for example Follmer and Sondermann (1986) and Jacod et al. (2000) for results about hedging strategies.

### 3.8. Finding a replication strategy

It is rare that we can actually “explicitly” compute a replication strategy, and rarer still that we can explicitly compute a hedging strategy. However, there are simple cases where miracles happen; and when there are no miracles, then we can often approximate hedging strategies accurately using numerical techniques.

A standard, and relatively simple, type of contingent claim is one which has the form

\[ H = f(S_T) \]

where \( S \) is the price of the risky security. The two most important examples (already discussed in Section 2) are

(i) The European call option: Here \( f(x) = (x - K)^+ \) for a constant \( K \), so the contingent claim is \( H = (S_T - K)^+ \). \( K \) is referred to as the strike price and \( T \) is the expiration time. In words, the European call option gives the holder the right to buy one unit of the security at the price \( K \) at time \( T \). Thus the (random) value of the option at time \( T \) is \( (S_T - K)^+ \).

(ii) The European put option: Here \( f(x) = (K - x)^+ \). This option gives the holder the right to sell one unit of the security at time \( T \) at price \( K \). Hence the (random) value of the option at time \( T \) is \( (K - S_T)^+ \).

The European call and put options are clearly related. Indeed we have

\[ (S_T - K)^+ - (K - S_T)^+ = S_T - K. \]

An important difference between the two is that \( (K - S_T)^+ \) is a bounded random variable with values in \([0, K]\), while \( (S_T - K)^+ \) is in general an unbounded random variable.

To illustrate the ideas involved, let us take \( R_t \equiv 1 \) by a change of the numeraire, and let us suppose that \( H = f(S_T) \) is a redundant claim. The value of a replicating
self-financing portfolio for the claim, at time $t$, is

$$V_t = E^* \{ f(S_T) | \mathcal{F}_T \} = a_0 S_0 + b_0 + \int_0^t a_s \, dS_s.$$  

We now make a series of hypotheses in order to obtain an easier analysis:

**Hypothesis 1.** $S$ is a Markov process under some equivalent local martingale measure $P^*$.

Under Hypothesis 1 we have

$$V_t = E^* \{ f(S_T) | \mathcal{F}_T \} = E^* \{ f(S_T) | \mathcal{F}_t \}.$$  

But measure theory tells us that there exists a function $\varphi(t, \cdot)$, for each $t$, such that

$$E^* \{ f(S_T) | \mathcal{F}_t \} = \varphi(t, S_t).$$

**Hypothesis 2.** $\varphi(t, x)$ is $C^1$ in $t$ and $C^2$ in $x$.

We now use Itô’s formula:

$$V_t = E^* \{ f(S_T) | \mathcal{F}_t \} = \varphi(t, S_t)
= \varphi(0, S_0) + \int_0^t \varphi_s'(s, S_s) \, dS_s + \frac{1}{2} \int_0^t \varphi''(s, S_s) \, d\langle S, S \rangle_s + \sum_{0 < s \leq t} \{ \varphi(s, S_s) - \varphi(s, S_{s^-}) - \varphi_s'(s, S_{s^-}) \Delta S_s \}.$$  

**Hypothesis 3.** $S$ has continuous paths. With Hypothesis 3 Itô’s formula simplifies:

$$V_t = \varphi(t, S_t) = \varphi(0, S_0) + \int_0^t \varphi_s'(s, S_s) \, dS_s
+ \frac{1}{2} \int_0^t \varphi''(s, S_s) \, d\langle S, S \rangle_s.$$  

Since $V$ is a $P^*$ martingale, the right side of (10) must also be a $P^*$ martingale. This is true if

$$\int_0^t \varphi_s'(s, S_s) \, ds + \frac{1}{2} \int_0^t \varphi''(s, S_s) \, d\langle S, S \rangle_s = 0.$$  

For Eq. (11) to hold, it is reasonable to require that $[S, S]$ have paths which are absolutely continuous almost surely. Indeed, we assume more than that: We assume a specific structure for $[S, S]$:

**Hypothesis 4.** $[S, S]_t = \int_0^t h(s, S_s)^2 \, ds$ for some jointly measurable function $h$ mapping $\mathbb{R}_+ \times \mathbb{R}$ to $\mathbb{R}$.

We then get that (11) certainly holds if $\varphi$ is the solution of the partial differential equation:

$$\frac{1}{2} h(s, x)^2 \frac{\partial^2 \varphi}{\partial x^2}(s, x) + \frac{\partial \varphi}{\partial s}(s, x) = 0.$$
with boundary condition \( \phi(T, x) = f(x) \). Note that if we combine Hypotheses 1–4, we have a continuous Markov process with quadratic variation \( \int_0^t h(s, S_s)^2 \, ds \). An obvious candidate for such a process is the solution of a stochastic differential equation

\[
dS_t = h(s, S_s) \, dB_s + b(s; S_s; r \leq s) \, ds,
\]

where \( B \) is a standard Wiener process (Brownian motion) under \( P \). \( S \) is a continuous Markov process under \( P^* \), with quadratic variation \( \int_0^t h(s, S_s)^2 \, ds \) as desired. The quadratic variation is a path property and is unchanged by changing to an equivalent probability measure \( P^* \) (see Protter, 1990, for example). But what about the Markov property? Why is \( S \) a Markov process under \( P^* \) when \( b \) can be path dependent?

Here we digress a bit. Let us analyze \( P^* \) in more detail. Since \( P^* \) is equivalent to \( P \), we can let \( Z = dP^* / dP \) and \( Z > 0 \) a.s. \( (dP) \). Let \( Z_t = E[Z | \mathcal{F}_t] \), which is clearly a martingale. By Girsanov’s theorem (see, e.g., Protter, 1990),

\[
\int_0^t h(s, S_s) \, dB_s - \int_0^t \frac{1}{Z_s} \, d\left[Z_s \int_0^s h(r, S_r) \, dB_r \right],
\]

is a \( P^* \) martingale.

Let us suppose that \( Z_t = 1 + \int_0^t H_s Z_s \, dB_s \), which is reasonable since we have martingale representation for \( B \) and \( Z \) is a martingale. We then have that (12) becomes

\[
\int_0^t h(s, S_s) \, dB_s - \int_0^t \frac{1}{Z_s} Z_s H_s h(s, S_s) \, ds = \int_0^t h(s, S_s) \, dB_s - \int_0^t H_s h(s, S_s) \, ds.
\]

If we choose \( H_s = b(s; S_s; r \leq s) / h(s, S_s) \), then we have

\[
S_t = \int_0^t h(s, S_s) \, dB_s + \int_0^t b(s; S_s; r \leq s) \, ds
\]

is a martingale under \( P^* \); moreover we have

\[
M_t = B_t + \int_0^t \left( b(s; S_s; r \leq s) / h(s, S_s) \right) \, ds
\]

is a \( P^* \) martingale; since \( [M, M]_t = [B, B]_t = t \), by Lévy’s theorem it is a \( P^* \)-Brownian motion (see, e.g., Protter, 1990), and we have

\[
dS_t = \ln(t, S_t) \, dM_t
\]

and thus \( S \) is a Markov process under \( P^* \). The last step in this digression is to show it is possible to construct such a \( P^* \)! Recall that the stochastic exponential of a semimartingale \( X \) is the solution of the “exponential equation”

\[
dY_t = Y_t \, dX_t; \quad Y_0 = 1.
\]

The solution is known in closed form and is given by

\[
Y_t = \exp \left( X_t - \frac{1}{2} [X, X]_t \right) \prod_{s \leq t} (1 + \Delta X_s) e^{-\Delta X_s}.
\]

If \( X \) is continuous then

\[
Y_t = \exp(X_t - \frac{1}{2} [X, X]_t),
\]

and it is denoted \( Y_t = \mathcal{E}(X) \). Recall we wanted \( dZ_t = H_t Z_t \, dB_t \); we let \( N_t = \int_0^t H_s \, dB_s \), and we have \( Z_t = \mathcal{E}(N)_t \). Then we set \( H_t = -b(t; S_t; r \leq t) / h(t, S_t) \) as planned and let

\[
\text{...}
\]
\[ dP^* = Z_T dP, \] and we have achieved our goal. Since \( Z_T > 0 \) a.s. (dP), we have that \( P \) and \( P^* \) are equivalent.

Let us now summarize the foregoing. We assume we have a price process given by

\[ dS_t = h(t, S_t) dB_t + b(t; S_t, r \leq t) dt. \]

We form \( P^* \) by \( dP^* = Z_T dP \), where \( Z_T = \mathbb{E}(N_T) \) and

\[ N_t = \int_0^t \frac{-b(s; S_r, r \leq s)}{h(s, S_r)} dB_s. \]

We let \( \phi \) be the (unique) solution of the boundary value problem.

\[ \frac{1}{2} h(t,x)^2 \frac{\partial^2 \phi}{\partial x^2} (t,x) + \frac{\partial}{\partial x} \phi(t,x) = 0 \quad (13) \]

and \( \phi(T,x) = f(x) \), where \( \phi \) is \( \mathcal{C}^2 \) in \( x \) and \( \mathcal{C}^1 \) in \( t \). Then

\[ V_t = \phi(t,S_t) = \phi(0,S_0) + \int_0^t \frac{\partial \phi}{\partial x}(s,S_s) dS_s. \]

Thus, under these four rather restrictive hypotheses, we have found our replication strategy! It is \( \phi = \frac{\partial \phi(s,S_s)}{\partial x} \). We have also of course found our value process \( V_t = \phi(t,S_t) \), provided we can solve the partial differential equation (13). However even if we cannot solve it in closed form, we can always approximate \( \phi \) numerically.

**Conclusion.** It is a convenient hypothesis to assume that the price process \( S \) of our risky asset follows a stochastic differential equation driven by Brownian motion.

**Important Comment.** Although our price process is assumed to follow the SDE

\[ dS_t = h(t, S_t) dB_t + b(t; S_t, r \leq t) dt, \]

we see that the PDE (13) does not involve the “drift” coefficient \( b \) at all! Thus the price and the replication strategy do not involve \( b \) either. The economic explanation of this is two fold: first, the drift term \( b \) is already reflected in the market price: it is based on the “fundamentals” of the security; second, what is important is the degree of risk involved, and this is reflected in the term \( h \).

**Remark.** Hypothesis 2 is not a benign hypothesis. Since \( \phi \) turns out to be the solution of a partial differential equation (given in (13)), we are asking for regularity of the solution. This is typically true when \( f \) is smooth (which of course the canonical example \( f(x) = (K-x)^+ \) is not!). The problem occurs at the boundary, not the interior. Thus for reasonable \( f \) we can handle the boundary terms. Indeed this analysis works for the cases of European calls and puts as we describe in Section 3.9.

**3.9. A special case**

In Section 3.8 we saw how it is convenient to assume \( S \) verifies a stochastic differential equation. Let us now assume \( S \) follows a linear SDE (= Stochastic Differential Equation) with constant coefficients:

\[ dS_t = \sigma S_t dB_t + \mu S_t dt; \quad S_0 = 1. \quad (14) \]
Let $X_t = B_t + \mu t$ and we have
\[
dS_t = S_t dX_t; \quad S_0 = 1
\]
so that
\[
S_t = \mathcal{E}(X)_t = e^{\sigma B_t + (\mu - \frac{1}{2} \sigma^2)t}.
\]
The process $S$ of (14) is known as geometric Brownian motion and has been used to study stock prices since at least the 1950s and the work of P. Samuelson. In this simple case the solution of the PDE (13) of Section 3.8 can be found explicitly, and it is given by
\[
\phi(x, t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(xe^{\sigma \sqrt{T-t} - (1/2) \sigma^2 (T-t)}) e^{-u^2/2} du.
\]
In the case of a European call option we have $f(x) = (x - K)^+$ and in this case we get
\[
\phi(x, t) = x \Phi \left( \frac{1}{\sigma \sqrt{T-t}} \left( \log \frac{x}{K} + \frac{1}{2} \sigma^2 (T-t) \right) \right)
- K \Phi \left( \frac{1}{\sigma \sqrt{T-t}} \left( \log \frac{x}{K} - \frac{1}{2} \sigma^2 (T-t) \right) \right).
\]
Here
\[
\Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{z} e^{-u^2/2} du.
\]
In the case of the call option we can also compute the replication strategy:
\[
a_t = \Phi \left( \frac{1}{\sigma \sqrt{T-t}} \left( \log \frac{S_t}{K} + \frac{1}{2} \sigma^2 (T-t) \right) \right).
\]
Third we can compute as well the price of the European call option (here we assume $S_0 = s$):
\[
V_0 = \phi(x, 0) = x \Phi \left( \frac{1}{\sigma \sqrt{T}} \left( \log \frac{x}{K} + \frac{1}{2} \sigma^2 T \right) \right) - K \Phi \left( \frac{1}{\sigma \sqrt{T}} \left( \log \frac{x}{K} - \frac{1}{2} \sigma^2 T \right) \right).
\]
These formulas, (16) and (17), are the celebrated Black–Scholes option formulas, with $R_t \equiv 1$.

This is a good opportunity to show how things change in the presence of interest rates. Let us now assume that we have a constant interest rate $r$, so that $R_t = e^{-rt}$. Then for example the formula (17) becomes
\[
V_0 = \phi(x, 0) = x \Phi \left( \frac{1}{\sigma \sqrt{T}} \left( \log \frac{x}{K} + \left( r + \frac{1}{2} \sigma^2 \right) T \right) \right)
- e^{-rT} K \Phi \left( \frac{1}{\sigma \sqrt{T}} \left( \log \frac{x}{K} + \left( r - \frac{1}{2} \sigma^2 \right) T \right) \right).
\]
These relatively simple, explicit, and easily computable formulas make working with European call and put options very simple. It is perhaps because of the beautiful
simplicity of this model that security prices are often assumed to follow geometric Brownian motions even when there is significant evidence that such a structure poorly models the real markets. Finally note that — as we observed earlier — the drift coefficient $\mu$ does not enter into the Black–Scholes formulas.

3.10. Other options in the Brownian paradigm: a general view

In Sections 3.8 and 3.9 we studied contingent claims of the form $H = f(S_T)$, that depend only on the final value of the price process. There we showed that the computation of the price and also the hedging strategy can be obtained by solving a partial differential equation, provided the price process $S$ is assumed to be Markov under $P^*$.

Other contingent claims can depend on the values of $S$ between 0 and $T$. A look-back option depends on the entire path of $S$ from 0 to $T$. To give an illustration of how to treat this phenomenon (in terms of calculating both the price and replication strategy of a look-back option), let us return to the very simple model of Geometric Brownian motion:

$$dS_t = \sigma S_t dB_t + \mu S_t dt.$$  \hspace{1cm} (19)

Proceeding as in Section 3.8 we change to an equivalent probability measure $P^*$ such that $B^*_t = B_t + \frac{1}{\sigma} \int_0^t \tau(B^*_\cdot, (t, T)) \, dB^*_t$ satisfying

$$dS_t = \sigma S_t dB^*_t.$$  \hspace{1cm} (19)

Let $F$ be a functional defined on $C[0, T]$, the continuous functions with domain $[0, T]$. Then $F(u) \in \mathbb{R}$, where $u \in C[0, T]$, and let us suppose that $F$ is Fréchet differentiable; let $DF$ denote its Fréchet derivative. Under some technical conditions on $F$ (see, e.g., Clark, 1970), if $H = F(B^*)$, then one can show

$$H = E^* \{H\} + \int_0^T p(DF(B^*; (t, T))) \, dB^*_t$$  \hspace{1cm} (20)

where $p(X)$ denotes the predictable projection of $X$. (This is often written “$E^* \{X|\mathcal{F}_t\}$” in the literature. The process $X = (X_t)_{0 \leq t \leq T}$, $E^* \{X_t|\mathcal{F}_t\}$ is defined for each $t$ a.s. The null set $N_t$ depends on $t$. Thus $E^* \{X_t|\mathcal{F}_t\}$ does not uniquely define a process, since if $N = \bigcup_{0 \leq t \leq T} N_t$, then $P(N_t) = 0$ for each $t$, but $P(N)$ need not be zero. The theory of predictable projections avoids this problem.) Using (19) we then have a formula for the hedging strategy:

$$a_t = \frac{1}{\sigma S_t} p(DF(\cdot, (t, T))).$$

If we have $H(\omega) = \sup_{0 \leq t \leq T} S_t(\omega) = S^*_T = F(B^*)$, then we can let $\tau(B^*)$ denote the random time where the trajectory of $S$ attains its maximum on $[0, T]$. Such an operation is Fréchet differentiable and

$$DF(B^*, \cdot) = \sigma F(B^*) \delta_{\tau(B^*)},$$

where $\delta_x$ denotes the Dirac measure at $x$. Let

$$M_{s,t} = \max_{s \leq u \leq t} \left( B^*_u - \frac{1}{2} \sigma u \right)$$
with \( M_t = M_{0,t} \). Then the Markov property gives
\[
E^* \{ DF(B^*, (t, T]) | \mathcal{F}_t \} (B^*) = E^* \{ \sigma F(B^*) 1_{\{M_t > M_t\}} | \mathcal{F}_t \} (B^*)
\]
\[
= \sigma S_t E^* \{ \exp(\sigma M_T - t); M_T > M_t(B^*) \}. 
\]

For a given fixed value of \( B^* \), this last expectation depends only on the distribution of the maximum of a Brownian motion with constant drift. But this distribution is explicitly known. Thus we obtain an explicit hedging strategy for this look-back option (see Goldman et al., 1979):
\[
a_t(\omega) = \left( -\log \frac{M_t}{S_t}(\omega) + \frac{\sigma^2(T-t)}{2} \right) \phi \left( \frac{-\log \frac{M_t}{X_t}(\omega) + \frac{1}{2} \sigma^2(T-t)}{\sigma \sqrt{T-t}} \right)
\]
\[
+ \sigma \sqrt{T-t} \varphi \left( \frac{-\log \frac{M_t}{S_t}(\omega) + \frac{1}{2} \sigma^2(T-t)}{\sigma \sqrt{T-t}} \right)
\]

where
\[
\phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{x} e^{-u^2/2} du
\]
\[ \text{and } \varphi(x) = \phi'(x). \]

The value of this look-back option is then
\[
V_0 = E^* \{ H \} = S_0 \left( \frac{\sigma^2 T}{2} + 2 \right) \phi \left( \frac{1}{2} \sigma \sqrt{T} \right) + \sigma \sqrt{T} S_0 \varphi \left( \frac{1}{2} \sigma \sqrt{T} \right). 
\]

Requiring that the claim be of the form \( H = F(B^*) \) where \( F \) is Fréchet differentiable is very restrictive. One can weaken this hypothesis substantially by requiring that \( F \) be only Malliavin differentiable. If we let \( D \) denote now the Malliavin derivative of \( F \), then Eq. (20) is still valid. Nevertheless explicit strategies and prices can be computed only in a few very special cases, and usually only when the price process \( S \) is Geometric Brownian motion.

4. American options

4.1. The general view

We begin with an abstract definition, in the case of a unique equivalent martingale measure.

**Definition.** We consider given an adapted process \( U \) and an expiration time \( T \). An **American Security** is a claim to the payoff \( U_t \) at a stopping time \( \tau \leq T \); the stopping time \( \tau \) is chosen by the holder of the security and is called the exercise policy.

We let \( V_t = \text{the price of the security at time } t \). One wants to find \( (V_t)_{0 \leq t \leq T} \) and especially \( V_0 \). Let \( V_t(\tau) \) denote the value of the security at time \( t \) if the holder uses
exercise policy \( \tau \). Let us further assume (only for simplicity) that \( R_t \equiv 1 \). Then
\[
V_t(\tau) = E^*\{U_t|\mathcal{F}_t\}
\]
(21)
where of course \( E^* \) denotes expectation with respect to the equivalent martingale measure \( P^* \). Let \( \mathcal{F}(t) = \{ \text{all stopping times with values in } [t, T] \} \).

**Definition.** A rational exercise policy is a solution to the optimal stopping problem
\[
V_0^* = \sup_{\tau \in \mathcal{F}(0)} V_0(\tau).
\]
(22)
We want to establish a price for an American security. That is, how much should one charge to give a buyer the right to purchase \( U \) in between \([0, T]\) at a stopping rule of his choice?

Suppose first that the supremum in (22) is achieved. That is, let us assume there exists a rule \( \tau^* \) such that \( V_0^* = V_0(\tau^*) \), where \( V_0^* \) is defined in (22).

**Lemma 1.** \( V_0^* \) is a lower bound for the no arbitrage price of our security.

**Proof.** Suppose it is not. Let \( V_0 < V_0^* \) be another price. Then one should buy the security at \( V_0 \) and use stopping rule \( \tau^* \) to purchase \( U \) at time \( \tau^* \). One then spends \(-U_{\tau^*}\), which gives an initial payoff of \( V_0^* = E^*\{U_{\tau^*}|\mathcal{F}_0\} \); one’s initial profit is \( V_0^* - V_0 > 0 \). This is an arbitrage opportunity. \( \square \)

To prove \( V_0^* \) is also an upper bound for the no arbitrage price (and thus finally equal to the price!), is more difficult.

**Definition.** A super-replicating trading strategy \( \theta \) is a self-financing trading strategy \( \theta \) such that \( \theta_tS_t \geq U_t \), all \( t \), \( 0 \leq t \leq T \), where \( S \) is the price of the underlying risky security on which the American security is based. (We are again assuming \( R_t \equiv 1 \).)

**Lemma 2.** Suppose a super-replicating strategy \( \theta \) exists, with \( \theta_0S_0 = V_0^* \). Then \( V_0^* \) is an upper bound for the no arbitrage price of the American security \( U \).

**Proof.** If \( V_0 > V_0^* \), then one can sell the American security and adapt a super-replicating trading strategy \( \theta \) with \( \theta_0S_0 = V_0^* \). One then has an initial profit of \( V_0 - V_0^* > 0 \), while we are also able to cover the payment \( U_t \) asked by the holder of the security at his exercise time \( \tau \), since \( \theta_\tau S_\tau \geq U_\tau \). Thus we have an arbitrage opportunity. \( \square \)

The existence of super-replicating trading strategies can be established using Snell Envelopes. A stochastic process \( Y \) is of “class D” if the collection \( \mathcal{H} = \{ Y_\tau; \tau \text{ a stopping time} \} \) is uniformly integrable.

**Theorem.** Let \( Y \) be a càdlàg, adapted process, \( Y > 0 \) a.s., and of “Class D”. Then there exists a positive càdlàg supermartingale \( Z \) such that

(i) \( Z \geq Y \), and for every other positive supermartingale \( Z' \) with \( Z' \geq Y \), also \( Z' \geq Z \);
(ii) \( Z \) is unique and also belongs to Class D;
(iii) For any stopping time $\tau$

$$Z_\tau = \text{ess sup}_{\tau \geq t} E\{Y_t|\mathcal{F}_t\}$$

($\nu$ also a stopping time).

For a proof consult Dellacherie and Meyer (1978) or Karatzas and Shreve (1998). $Z$ is called the Snell Envelope of $Y$.

One then needs to make some regularity hypotheses on the American security $U$. For example if one assumes $U$ is a continuous semimartingale and $E^*\{[U,U]_T\} < \infty$, it is more than enough. One then uses the existence of Snell envelopes to prove:

**Theorem.** Under regularity assumptions (for example $E^*\{[U,U]_T\} < \infty$ suffices) there exists a super-replicating trading strategy $\theta$ with $0, S_t \geq k$ for all $t$ for some constant $k$ and such that $0, S_0 = V_0^*$. A rational exercise policy is

$$\tau^* = \inf\{t > 0: Z_t = U_t\},$$

where $Z$ is the Snell Envelope of $U$ under $P^*$.

4.2. The American call option

Let us here assume that for a price process $(S_t)_{0 \leq t \leq T}$ and a bond process $R_t \equiv 1$, there exists a unique equivalent martingale measure $P^*$ which means that there is No Arbitrage and the market is complete.

**Definition.** An American call option with terminal time $T$ and strike price $K$ gives the holder the right to buy the security $S$ at any time $\tau$ between $0$ and $T$, at price $K$.

It is of course reasonable to consider the random time $\tau$ where the option is exercised to be a stopping time, and it is standard to assume that it is then $(S_\tau - K)^+$, corresponding to which rule $\tau$ the holder uses.

We note first of all that since the holder of the option is free to choose the rule $\tau \equiv T$, he or she is always in a better position than the holder of a European call option, whose worth is $(S_T - K)^+$. Thus the price of an American call option should be bounded below by the price of the corresponding European call option.

Following Section 4.1 we let

$$V_\tau(\tau) = E^*\{U_\tau|\mathcal{F}_\tau\} = E^*\{(S_\tau - K)^+|\mathcal{F}_\tau\}$$

denote the value of our American call option at time $\tau$ assuming $\tau$ is the exercise rule.

We then have that the price is

$$V_0^* = \sup_{0 \leq \tau \leq T} E^*\{(S_\tau - K)^+\}. \quad (23)$$

We note however that $S = (S_t)_{0 \leq t \leq T}$ is a martingale under $P^*$, and since $f(x) = (x - K)^+$ is a convex function we have $(S_\tau - K)^+$ is a submartingale under $P^*$; hence from (23) we have

$$V_0^* = E^*\{(S_T - K)^+\}$$
since \( t \to \mathbb{E}^\omega \{ (S_t - K)^+ \} \) is an increasing function, and the sup — even for stopping times — of the expectation of a submartingale is achieved at the terminal time (this can be easily seen as a trivial consequence of the Doob–Meyer decomposition theorem). This leads to the following result (however the analogous result is not true for American put options, or even for American call options if the underlying stocks pay dividends):

**Theorem.** In a complete market (with no arbitrage) the price of an American call option with terminal time \( T \) and strike price \( K \) is the same as the price for a European call option with the same terminal time and strike price.

**Corollary.** If the price process \( S_t \) follows the SDE

\[
dS_t = \sigma S_t dB_t + \mu S_t dt;
\]

then the price of an American call option with strike price \( K \) and terminal time \( T \) is the same as that of the corresponding European call option and is given by the formula (III.1.4) of Black and Scholes.

We note that while we have seen that the prices of the European and American call options are the same, we have said nothing about the replication strategies.

4.3. Backwards stochastic differential equations and the American put option

Let \( \xi \) be in \( L^2 \) and suppose \( f: \mathbb{R}_+ \times \mathbb{R} \to \mathbb{R} \) is Lipschitz in space. Then a simple backwards ordinary differential equation (\( \omega \) by \( \omega \)) is

\[
Y_t(\omega) = \xi(\omega) + \int_t^T f(s, Y_s(\omega)) \, ds.
\]

However if \( \xi \in L^2(\mathcal{F}_T, d\mathbb{P}) \) and one requires that a solution \( Y = (Y_t)_{0 \leq t \leq T} \) be adapted (that is, \( Y_t \in \mathcal{F}_t \)), then the equation is no longer simple. For example if \( Y_t \in \mathcal{F}_t \) for every \( t, 0 \leq t \leq T \), then one has

\[
Y_t = \mathbb{E} \left\{ \xi + \int_t^T f(s, Y_s) \, ds \mid \mathcal{F}_t \right\}.
\]

An equation such as (24) is called a Backwards Stochastic Differential Equation. Next we write

\[
Y_t = \mathbb{E} \left\{ \xi + \int_0^T f(s, Y_s) \, ds \mid \mathcal{F}_t \right\} - \int_0^t f(s, Y_s) \, ds
\]

\[
= M_t - \int_0^t f(s, Y_s) \, ds
\]

where \( M \) is the martingale \( \mathbb{E} \{ \xi + \int_0^T f(s, Y_s) \, ds \mid \mathcal{F}_t \} \). We then have

\[
Y_T - Y_t = M_T - M_t - \left( \int_0^T f(s, Y_s) \, ds - \int_0^t f(s, Y_s) \, ds \right)
\]

\[
= M_T - M_t - \int_t^T f(s, Y_s) \, ds
\]
or, the equivalent equation:

\[ Y_t = \xi + \int_t^T f(s, Y_s) \, ds - (M_T - M_t). \]  

(25)

Next let us suppose we are solving (24) on the canonical space for Brownian motion. Then we have that the martingale representation property holds, and hence there exists a predictable \( Z \in \mathcal{L}(B) \) such that

\[ M_t = M_0 + \int_0^t Z_s \, dB_s, \]

where \( B \) is Brownian motion. We have that (25) becomes

\[ Y_t = \xi + \int_t^T f(s, Y_s) \, ds - \int_t^T Z_s \, dB_s. \]  

(26)

Thus to find an adapted \( Y \) that solves (24) is equivalent to find a pair \((Y, Z)\) with \( Y \) adapted and \( Z \) predictable that solve (26).

Now that one has introduced \( Z \), one can consider a more general version of (26) of the form

\[ Y_t = \xi + \int_t^T f(s, Y_s, Z_s) \, ds - \int_t^T Z_s \, dB_s. \]  

(27)

We next wish to consider a more general equation than (27), however: Backward Stochastic Differential Equations where the solution \( Y \) is forced to stay above an obstacle. This can be formulated as follows (here we follow El Karoui et al., 1997):

\[
\begin{cases}
Y_t = \xi + \int_t^T f(s, Y_s, Z_s) \, ds + K_T - K_t - \int_t^T Z_s \, dB_s \\
y_t \geq U_t \quad (U \text{ is optional}) \\
K \text{ is continuous, increasing, adapted, } K_0 = 0, \text{ and } \int_0^T (Y_t - U_t) \, dK_t = 0.
\end{cases}
\]  

(28)

The obstacle process \( U \) is given, as are the random variables \( \xi \) and the function \( f \), and the unknowns to find are \((Y, Z, K)\). Once again it is \( Z \) that makes both \( Y \) and \( K \) adapted.

**Theorem** (El Karoui et al., 1997). Let \( f \) be Lipschitz in \((y, z)\) and assume \( E\{\sup_{0 \leq t \leq T} (U_t^+)^2\} < \infty \). Then there exists a unique solution \((Y, Z, K)\) to Eq. (28).

Two proofs are given in El Karoui et al., 1997: one uses the Skorohod problem, a priori estimates and Picard iteration; the other uses a penalization method.

Now let us return to American options. Let \( S \) be the price process of a risky security and let us take \( R_t \equiv 1 \). An American put option then takes the form \((K - S_t)^+\) where \( K \) is a strike price and the exercise rule \( \tau \) is a stopping time with \( 0 \leq \tau \leq T \). Thus we should let \( U_t = (K - S_t)^+ \), and if \( X \) is the Snell envelope of \( U \), we see from
Section 4.1 that a rational exercise policy is
\[ \tau^* = \inf \{ t > 0 : X_t = U_t \} \]
and that the price is \( V_0^* = V_0(\tau^*) = E^* \{ U_{\tau^*} \mid \mathcal{F}_0 \} = E^* \{ (K - S_{\tau^*})^+ \} \). Therefore finding the price of an American put option is related to finding the Snell envelope of \( U \).
Recall that the Snell envelope is a supermartingale such that
\[ X_v = \text{ess sup}_{v \geq t} E \{ U_v \mid \mathcal{F}_v \} \]
where \( v \) is also a stopping time.

We consider the situation where \( U_t = (K - S_t)^+ \) and \( \xi = (K - S_T)^+ \). We then have

**Theorem** (El Karoui et al., 1997). Let \( (Y, K, Z) \) be the solution of (28). Then
\[ Y_t = \text{ess sup}_{t \leq s \leq T} E \left\{ \int_t^s f(s, Y_s, Z_s) \, ds + U_s \mid \mathcal{F}_t \right\}. \]

**Proof (Sketch).**
In this case
\[ Y_t = U_T + \int_t^T f(s, Y_s, Z_s) \, ds + K_T - K_t - \int_t^T Z_s \, dB_s, \]
hence
\[ Y_0 - Y_t = -\int_t^\gamma f(s, Y_s, Z_s) \, ds + (K_t - K_\gamma) + \int_t^\gamma Z_s \, dB_s, \]
and since \( Y_t \in \mathcal{F}_t \) we have
\[ Y_t = E \left\{ \int_t^\gamma f(s, Y_s, Z_s) \, ds + Y_\gamma + (K_\gamma - K_t) \mid \mathcal{F}_t \right\} \]
\[ \geq E \left\{ \int_t^\gamma f(s, Y_s, Z_s) \, ds + U_\gamma \mid \mathcal{F}_t \right\}. \]
Next let \( \gamma_t = \inf \{ t \leq u \leq T : Y_u = U_u \} \), with \( \gamma_t = T \) if \( Y_u > U_u, t \leq u \leq T \). Then
\[ Y_t = E \left\{ \int_t^{\gamma_t} f(s, Y_s, Z_s) \, ds + Y_{\gamma_t} + K_{\gamma_t} - K_t \mid \mathcal{F}_t \right\}. \]
However on \( [t, \gamma_t) \) we have \( Y > U \), and thus \( \int_t^{\gamma_t} (Y_s - U_s) \, dK_s = 0 \) implies that \( K_{\gamma_t} - K_t = 0 \); however \( K \) is continuous by assumption, hence \( K_{\gamma_t} - K_t = 0 \). Thus (using \( Y_{\gamma_t} = U_{\gamma_t} \)):
\[ Y_t = E \left\{ \int_t^{\gamma_t} f(s, Y_s, Z_s) \, ds + U_{\gamma_t} \mid \mathcal{F}_t \right\} \]
and we have the other implication. \( \Box \)

The next corollary shows that we obtain the price of an American put option via reflected backwards stochastic differential equations.

**Corollary.** The American put option has the price \( Y_0 \), where \( (Y, K, Z) \) solves the reflected obstacle backwards SDE with obstacle \( U_t = (K - S_t)^+ \) and where \( f = 0 \).
Proof. In this case the previous theorem becomes

\[ Y_0 = \text{ess sup}_{0 \leq t \leq T_a} E \{ U_t | \mathcal{F}_t \}, \]

and \( U_t = (K - S_t)^+ \). \( \Box \)

This relationship between the American put option and backwards SDEs can be exploited to price numerically an American put option; there is recent work in this direction due to Soledad Torres, Jaime San Martin and this author (Protter et al., 2000) as well as work due to Bally and Pagès (2000). A more traditional method is to use numerical methods with variational partial differential equations.

We note that one can generalize these results to American Game Options, using Forward–Backward Reflected Stochastic Differential Equations. See, e.g., Ma and Cvitanić (1999) or the new “Game Options” introduced by Kifer (2000).

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